



Amendments to the Claims:

 Claim 1. (Currently Amended) A method for in-place memory management in a Digital Signal Processing (DSP) architecture performing a Fast Fourier Transformation (FFT) upon a sequence of N data points, said sequence numbered from 0 to $N-1$, the method comprising:

storing each of said data points numbered from 0 to $(N/2)-1$ in a first memory space X and each of said data points numbered $N/2$ to $N-1$ in a second memory space Y; and
for each FFT stage 0 data point grouping comprising a first data point of said data points in said first memory space X and a corresponding second data point of said data points in said second memory space Y:

determining a the parity of a data point memory index corresponding to said first and second data points;

 storing, if said parity is of a first parity value, the results of an FFT operation upon said first data point at the memory address in said first memory space X from which said first data point was fetched and the result of an FFT operation upon said second data point at the memory address in said second memory space Y from which said second data point was fetched; and

storing, if said parity is of a second parity value, the results of an FFT operation upon said first data point at the memory address in said second memory space Y from which said second data point was fetched and the result of an FFT operation upon said second data point at the memory address in said first memory space X from which said first data point was fetched.

Claim 2. (Original) A method according to claim 1 and further comprising:

for any FFT stage Z subsequent to stage 0 and each FFT stage Z data point grouping comprising a first data point in said first memory space X and a corresponding second data point in said second memory space Y, storing the results of an FFT operation upon said first data point at the memory address in said first memory space X from which said first data point was fetched and the results of an FFT operation upon said second data point at the memory address in said second memory space Y from which said second data point was fetched.

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Claim 3. (New) A method comprising:

determining a parity of a memory index, where a first data point of a pair of input data points of a first stage of a Fast Fourier Transform calculation is stored in a first memory space at a first address corresponding to said memory index and a second data point of said pair is stored in a second memory space at a second address corresponding to said memory index;

if said parity is of a first parity value, storing a first output data point of said first stage at said first address in said first memory space and a second output data point of said first stage at said second address in said second memory space; and

if said parity is of a second parity value, storing said first output data point at said second address in said second memory space and said second output data point at said first address in said first memory space.

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Claim 4. (New) The method of claim 3, further comprising:

storing an output data point of said second stage that is associated with said first output data point at the address in the memory space where said first output data point was stored; and

storing an output data point of said second stage that is associated with said second output data point at the address in the memory space where said second output data point was stored.

Claim 5. (New) A method comprising:

determining, based at least on a parity of a memory index, whether to store an output data point of a first stage of a Fast Fourier Transform calculation in a first memory space at a first address or in a second memory space at a second address, where a first data point of a pair of input data points of said first stage is stored in said first memory space at said first address and a second data point of said pair is stored in said second memory space at said second address, and where said first address and said second address both correspond to said memory index.

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Page 6

Feb 11
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Claim 6. (New) A digital signal processor comprising:

a first memory space to store a first data point of a pair of input data points of a first stage of a Fast Fourier Transform calculation at a first address corresponding to a memory index;

a second memory space to store a second data point of said pair at a second address corresponding to said memory index; and

means for determining, based at least on a parity of said memory index, whether to store an output data point of said first stage in said first memory space at said first address or in said second memory space at said second address.
